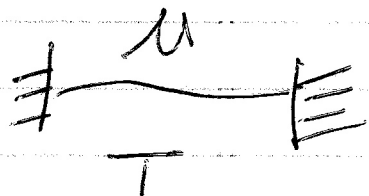


(ii) Non-trivial

Derive NL equation for string with tension T (1D)



- end point fixed
 $\frac{dy}{dx}(0) = \frac{dy}{dx}(L) = 0$
 all t
 $= \frac{dy}{dx}(x, t_{2,1}) = 0$

~~###~~ $\sum_i = \int dx$

$$S = \int_{t_1}^{t_2} dt \int_0^L dx \mathcal{L}$$

↓
Lagrangian density

G.C. $y(x, t)$

$$\mathcal{L} = \frac{1}{2} \mu \left(\frac{dy}{dx}(x, t) \right)^2 - U$$

Now

$$U = \int_0^L ds T = \int_0^L dx \sqrt{\frac{ds}{dx}} T \quad (\text{ref.}) \rightarrow \text{correl.}$$

↓
potential energy stored in string

but $ds^2 = dx^2 + dy^2$
 $= dx^2 \left(1 + \left(\frac{dy}{dx} \right)^2 \right)$

so $U = \int_0^L dx T (1 + (dy/dx)^2)^{1/2}$

$\Rightarrow \mathcal{L} = \frac{1}{2} \mu (\partial_t y(x,t))^2 - T (1 + (\partial_x y)^2)^{1/2}$

so

$$S = \int dt \int_0^L dx \left\{ \frac{1}{2} \mu (\partial_t y)^2 - T (1 + (\partial_x y)^2)^{1/2} \right\}$$

$$\delta S = \int_{t_1}^{t_2} dt \int_0^L dx \left\{ \frac{\partial \mathcal{L}}{\partial y_t} \delta y_t + \frac{\partial \mathcal{L}}{\partial y_x} \delta y_x \right\}$$

$$= \int_0^L dx \left. \frac{\partial \mathcal{L}}{\partial y_t} \delta y \right|_{t_1}^{t_2} - \int_{t_1}^{t_2} dt \int_0^L dx \frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial y_t} \right) \delta y$$

$$+ \int_{t_1}^{t_2} dt \left. \frac{\partial \mathcal{L}}{\partial y_x} \delta y \right|_0^L - \int_{t_1}^{t_2} dt \int_0^L dx \frac{\partial}{\partial x} \left(\frac{\partial \mathcal{L}}{\partial y_x} \right) \delta y$$

no variation δy at t_2

fixed e.o.p. at t_1

so

$$\delta S = 0 \quad (\text{PLA})$$

$$\frac{\partial}{\partial t} \left(\frac{\partial \mathcal{L}}{\partial y_t} \right) + \frac{\partial}{\partial x} \left(\frac{\partial \mathcal{L}}{\partial y_x} \right) = 0$$

Lagrange
Egn.

Now $\frac{\partial \mathcal{L}}{\partial y_t} = \mu y_t$

$$\frac{\partial \mathcal{L}}{\partial y_x} = \frac{-T \partial y / \partial x}{\left[1 + \left(\frac{\partial y}{\partial x}\right)^2\right]^{1/2}}$$

$$\frac{\partial}{\partial t} (\mu y_t) - \frac{\partial}{\partial x} \left(\frac{T \partial y / \partial x}{\left[1 + (\partial y / \partial x)^2\right]^{1/2}} \right) = 0$$

- non/linear eqn. for waves on clamped string.

- linearizing for μ, T const

$$\Rightarrow \left[\mu \frac{\partial^2 y}{\partial t^2} = T \frac{\partial^2 y}{\partial x^2} \right]$$

wave eqn,
as expected!

→ Conservation and Symmetry } Read Chapt. 2
 $L \neq \bar{L}$

- Energy

→ will show if $\partial_t L = 0$ (no explicit time dependence)
 i.e. homogeneity of time, unless broken by external input

⇒ energy conservation
 homogeneity of time, for closed system.

$$\begin{aligned} \text{Now } \frac{dL}{dt} &= \frac{\partial L}{\partial t} + \frac{\partial L}{\partial q} \dot{q} + \frac{\partial L}{\partial \dot{q}} \ddot{q} \\ &\left[\text{can shift } \frac{\partial L}{\partial t} = 0, \text{ arbitrarily} \right] \frac{\partial L}{\partial \dot{q}} \ddot{q} \\ &= \frac{\partial L}{\partial q} \dot{q} + \frac{\partial L}{\partial \dot{q}} \ddot{q} \end{aligned}$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \Rightarrow$$

$$\begin{aligned} \frac{dL}{dt} &= \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \dot{q} + \frac{\partial L}{\partial \dot{q}} \ddot{q} \\ &= \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \dot{q} \right) \end{aligned}$$

$$\frac{d}{dt} \left(\dot{q} \frac{\partial L}{\partial \dot{q}} - L \right) = 0$$

so

$$E = \dot{q} \frac{\partial L}{\partial \dot{q}} - L \equiv \text{energy}$$

- const. energy

- defines conservative system

i.e. one with $\partial_t L = 0$,

Note: - Hamiltonian H defined s/f

$$H = p \dot{q} - L \quad \left\{ \begin{array}{l} \text{where } p = \partial L / \partial \dot{q} \\ \text{and eliminate } \dot{q} \\ \text{in favor of } p. \end{array} \right.$$

- in general

$$H \neq E$$

($H = E$ for conservative)

- can define H when $\partial_t L \neq 0$,
so energy not conserved.

Linear Momentum

→ For closed system, homogeneity of space \Rightarrow mechanical properties unchanged by any parallel displacement of the system in space

i.e. can shift origin of coordinate system, physics invariant upon
 $\underline{r} \rightarrow \underline{r} + \underline{\epsilon}$

$$\delta L = \sum_i \frac{\partial L}{\partial \underline{r}_i} \cdot \underline{\epsilon} = \underline{\epsilon} \cdot \sum_i \frac{\partial L}{\partial \underline{r}_i}$$

$$\delta L = 0 \Rightarrow \sum_i \frac{\partial L}{\partial \underline{r}_i} = 0, \text{ so}$$

using Lagrange's Eqn.

$$\sum_i \frac{d}{dt} \left(\frac{\partial L}{\partial \underline{v}_i} \right) = 0$$

but recall: $\frac{\partial L}{\partial \underline{v}_i} = \underline{p}_i \Rightarrow$ momentum

$$\underline{\infty} \quad \frac{d\underline{p}}{dt} = 0 \quad \underline{p} = \sum_i \partial L / \partial \underline{v}_i$$

momentum conserved!

$$\therefore \text{For } \underline{F}_i = - \frac{\partial U}{\partial \underline{r}_i} = \frac{\partial L}{\partial \underline{r}_i} = 0$$

gen. force, = 0 ~~and~~ hence, of spec.

gen. momentum conserved.

Angular Momentum

→ isotropy of space, for closed system,

⇒ physics invariant under infinitesimal rotation.

i.e. $\underline{d\phi} \equiv$ vector infinitesimal rotation

$|\underline{d\phi}| \rightarrow$ magnitude, $\frac{\underline{d\phi}}{|\underline{d\phi}|} \rightarrow$ direction of axis

then upon rotation \Rightarrow

$$\underline{dr} = \underline{d\phi} \times \underline{r}$$

$$\underline{dv} = \underline{d\phi} \times \underline{v}$$

velocities also change.

\Rightarrow So, isotropy of space $\Rightarrow \delta L = 0$
upon infinitesimal rotation

So

$$\delta L \Big|_{\text{rotation}} = \sum_i \left(\underbrace{\frac{\partial L}{\partial \underline{r}_i}}_{\underline{p}_i} \cdot d\underline{r}_i + \frac{\partial L}{\partial \underline{v}_i} \cdot d\underline{v}_i \right)$$

So symmetry under rotation \Rightarrow

$$\delta L = 0 = \sum_i \left(\underline{p}_i \cdot d\underline{\varphi} \times \underline{r}_i + \underline{p}_i \cdot d\underline{\varphi} \times \underline{v}_i \right)$$

re-arranging the terms:

$$\delta L = 0 = d\underline{\varphi} \cdot \sum_i \left(\underline{r}_i \times \underline{p}_i + \overset{\underline{v}_i}{\downarrow} \cdot \underline{r}_i \times \underline{p}_i \right)$$

$$= d\underline{\varphi} \cdot \frac{d}{dt} \sum_i \left(\underline{r}_i \times \underline{p}_i \right) = 0$$

$$\Rightarrow \delta L = 0 \Rightarrow \frac{d}{dt} \underline{L} = 0, \quad \underline{L} = \sum_i \underline{r}_i \times \underline{p}_i$$

\Rightarrow rotational invariance \Rightarrow angular momentum conserved.

Note: Angular momentum depends on choice of origin, except when system at rest, as a whole.

i.e.
$$\underline{L} = \sum_i \underline{r}_i \times \underline{p}_i$$

$$\underline{r}_i \rightarrow \underline{r}'_i + \underline{q}$$

$$\begin{aligned} \underline{L} &= \sum_i \underline{r}'_i \times \underline{p}_i + \sum_i \underline{q} \times \underline{p}_i \\ &= \underline{L}' + \underline{q} \times \underline{P} \end{aligned}$$

N.B.: Do problem 3, section 9 of L&L.
Approach intuitively \rightarrow see below.

Observe:

time homogeneity $\leftrightarrow t \rightarrow t_0 + t' \leftrightarrow \partial_t L = 0 \leftrightarrow$ energy conservation

spatial homogeneity $\leftrightarrow \underline{x} \rightarrow \underline{x}' + \underline{c} \leftrightarrow$ linear momentum conservation

$$\partial_{\underline{x}} L = 0$$

rotational invariance $\Rightarrow \phi = \phi' + \delta\phi \Rightarrow$ angular momentum conservation
 $\partial L / \partial \phi = 0$

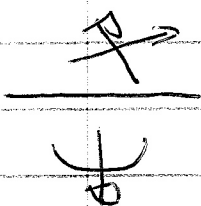
\Rightarrow suggestive of connection between:

symmetry \rightarrow ignorable or 'cyclic' coordinate \rightarrow conservation property/law
 $(\partial L / \partial q = 0)$

\Rightarrow Noether's Theorem!

Ex. Which components $\underline{p} \perp$ conserved in following fields?

a.) inf. homog. plane: 2 components $\underline{p} \parallel$ plane
 \perp perp to plane

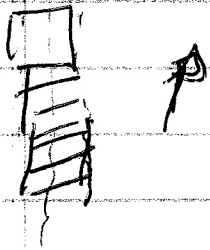


b.) inf. homog. cylinder



\perp component along axis
 \underline{p} component along axis

c.) inf. homogeneous rectangular prism



$\rightarrow P_z, \parallel \text{ prism}$

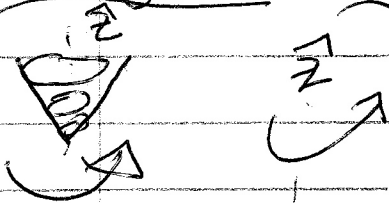
d.) Torus L_z only.



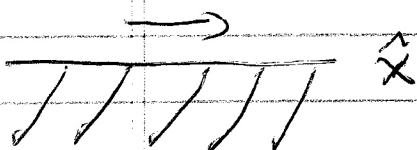
e.) Two points L_x only



f.) homogeneous cone L_z only

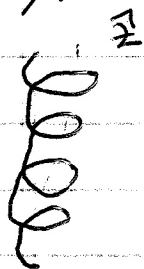


g.) infinite half plane plate



P_x only

h.) conf. homogeneous
cylindrical helix.



$h \equiv$ pitch
(vert. dist. m
/ rotation)

Invariant: $\delta\phi$ rotation

+ $\frac{\delta z}{2\pi} h$ vert.
translation

$$\text{i.e. } \delta L = \frac{\partial L}{\partial z} \delta z + \frac{\partial L}{\partial \phi} \delta \phi$$

$$\delta z = \frac{h}{2\pi} \delta \phi, \quad \frac{\partial L}{\partial z} = \frac{d}{dt} P_z$$

$$\Rightarrow \delta L = \frac{h}{2\pi} P_z \delta \phi + L_z \delta \phi$$

$$= \delta \phi \left(\frac{h}{2\pi} \dot{P}_z + \dot{L}_z \right)$$

$$\delta L = 0 \Rightarrow \frac{h}{2\pi} P_z + L_z = \text{const.}$$

Now... can also consider scale
symmetry \Rightarrow Virial Theorems.

V.B. Virial Thms are simple, interesting
and useful \rightarrow esp in astrophysics.

Re: scale symmetry \Rightarrow

$$\text{if } U(\alpha \underline{r}_1, \alpha \underline{r}_2, \dots, \alpha \underline{r}_n) = \alpha^k U(\underline{r}_1, \underline{r}_2, \dots, \underline{r}_n)$$

i.e. n -scale variables

$\Rightarrow U$ is homogeneous. (related to scale invariance)

Many relevant U are homogeneous, i.e.

harmonic oscillator: $k=2$

Coulomb/gravity: $k=-1$

etc. \Rightarrow homogeneous $U \Rightarrow$ power law structure,

Now, recall:

EOM from $\delta \int dt L = 0$, so if

$L \rightarrow \alpha L$, EOM unchanged.

\downarrow
const. factor

\Rightarrow Multiplying Lagrangian by constant factor leaves physics unchanged.

→ So, for homogeneous U , can generate class of rescalings which multiply Lagrangian by const. factor

⇒ same EOM.

→ such rescalings define basic class of relations between quantities.

→ useful for basic story/characteristics w/o detailed work.

$$\text{Now: } S = \int dt \left(\frac{1}{2} m \dot{\underline{r}}^2 - U(\underline{r}) \right)$$

$$\underline{r} \rightarrow \alpha \underline{r}'$$

$$t \rightarrow \beta t'$$

$$S = \int dt' \left(\frac{1}{2} m \frac{\alpha^2}{\beta^2} \dot{r}'^2 - \alpha^k U(r') \right)$$

so if $\alpha^2/\beta^2 \sim \alpha^k \Rightarrow L$ multiplied by factor and δS invariant.

⇒

$\beta \sim \alpha^{1-k/2}$ defined
time-space rescaling
leaving EOM unchanged.

i.e.

$$t'/t \sim (\ell'/\ell)^{1-k/2}$$

Equivalently:

$$\dot{v}/v \sim \alpha^{k/2} \sim (\ell'/\ell)^{k/2}$$

$$E'/E \sim (\ell'/\ell)^k$$

$$L'/L \sim (\ell'/\ell)^{1+k/2}$$

→ works
only for
homog. fn.

→ Eg. ① $U \sim Z$ gravity $k=2$

$$\Rightarrow t'/t \sim (\ell'/\ell)^{1/2}$$

fall time \sim square of amplitude.

$$\textcircled{b} \quad U \sim r^2 \quad k = 2 \quad (\text{h.o.})$$

$$t'/t \sim l^0 \Rightarrow \text{period indep. of amplitude.}$$

$$\textcircled{c} \quad U \sim r^{-1} \quad k = -1$$

$$t'/t \sim (l'/l)^{3/2}$$

$$\text{Period} \sim (\text{radius})^{3/2} \Rightarrow \text{Kepler's 3rd Law.}$$

Homogeneous $U \rightarrow$ Virial Thms!

What is a Virial Thm?

- consider a system of particles

∴

$$- \frac{d}{dt} \sum_i \underline{p}_i \cdot \underline{x}_i = \sum_i \underline{p}_i \cdot \dot{\underline{x}}_i + \sum_i \dot{\underline{p}}_i \cdot \underline{x}_i$$

$$= \underbrace{2T}_{KE} - \sum_i \frac{\partial U}{\partial \underline{x}_i} \cdot \underline{x}_i$$

Now consider $\langle \left(\sum_i \underline{p}_i \cdot \underline{x}_i \right) \rangle \rightarrow$ time avg.

$$\langle A \rangle = \frac{1}{T} \int_0^T A \quad \text{as } T \rightarrow \infty$$

So if $\sum_i \underline{p}_i \cdot \underline{x}_i$ bounded in time

$$\left\langle \frac{d}{dt} \sum_i \underline{p}_i \cdot \underline{x}_i \right\rangle = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T dt \left(\frac{d}{dt} \sum_i \underline{p}_i \cdot \underline{x}_i \right)$$

$\Rightarrow 0$

so

$$\langle T \rangle = \left\langle \sum_i \frac{\partial U}{\partial \underline{x}_i} \cdot \underline{x}_i \right\rangle$$

Now, if $U = U(\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n)$
and U homogeneous

$$\text{i.e. } U(\alpha \underline{x}_1, \dots, \alpha \underline{x}_n) = \alpha^k U(\underline{x}_1, \dots, \underline{x}_n)$$

$$\text{Then } \boxed{\langle T \rangle = k \langle U \rangle}$$

and also, of course, have:

$$T + U = E = \langle T \rangle + \langle U \rangle$$

so

$$2\langle T \rangle = k\langle U \rangle$$

$$E = \langle T \rangle + \langle U \rangle$$

⇒

$\langle U \rangle = \frac{2}{k+2} E$ $\langle T \rangle = kE/k+2$
--

check:

$$\rightarrow k = 2$$

$$\langle U \rangle = E/2$$

$$\langle T \rangle = E/2$$

equipartition in H.O.

$$\rightarrow k = -4$$

$$\langle U \rangle = E$$

$$\langle T \rangle = -E$$

$$\leadsto \langle T \rangle = -E$$

\Rightarrow total energy negative for gravitationally bound cluster

i.e. must have bound state for time avg. to converge.

Who cares / why care?

- virial thus relate energies to potential structure
- can relate measured k.E. (Doppler spectroscopy) to energies
- virial is single # characterizing a cluster

$$F(\underline{x}, \underline{v}, t) \rightarrow V(\underline{x}, t) \rightarrow \langle T \rangle, \langle U \rangle, E.$$

Boltzmann \rightarrow fluid \rightarrow virial

\downarrow
velocity
moment

\downarrow
 $\sum_c \rightarrow$ integral in space.